

# HSU-STRUCTURE ON H-STRUCTURE MANIFOLDS II

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**Abstract**— In this paper we have studied Hsu-structure & H-structure manifolds and obtained with constant holomorphic sectional curvature. On this communication we prove that every  $2m$  dimensional connected NK-manifold of pointwise constant holomorphic sectional curvature is an Einstein manifold

**Index Terms**— H-structure manifold , Hsu-structure ,Curvature tensor almost complex , almost product and almost tangent structures, NK-manifold.

**Mathematical Classification** : 53C15, 53C25

## I. INTRODUCTION

Let  $F$  be a  $(1,1)$  tensor field on  $C^\infty$   $n$ -dimensional differentiable manifold  $M$ , such that

$$F^2(X) = a^r X, \quad (1)$$

where  $a$  is a real or a purely imaginary number and  $X$  an arbitrary vector field on  $M$ , Clearly,  $F$  is an endomorphism of the tangent space  $T_p(M)$ , for every point  $p \in M$ .  $F$  gives a differentiable structure on  $M$  called Hsu-structure defined by (1).

Let there be defined on  $V_n$ , a vector valued linear function  $F$  of class  $C$  such that

$$F^2 = a^r I_n \quad 0 \leq r \leq n$$

where  $r$  is an integer and  $a$  is real or imaginry number. Then  $F$  is called Hsu – structure and  $V_n$  is called the **Hsu – structure manifold**.

If  $a^{r/2} = 0$ , we have an almost tangent structure.

If  $a^{r/2} \neq 0$ , we have a  $\pi$  – structure which is known from G. Legrand in [4], (1956), Especially if  $a^r = 1$ , we have an almost product structure, if  $a^r = -1$ , we have the well known almost complex structure, ( $J^2 X = -X$ )

If the above mentioned Hsu-structure  $F$  is equipped with a Hermitian metric  $g$  such that

$$g(FX, FY) + a^r g(X, Y) = 0.$$

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for any vector fields  $X, Y$  on  $M$ , then  $(g, F)$  is called H-structure and  $M$  is said to be H-structure manifold. Many authors studied H-structure manifolds: K.L. Duggal in [1] and [2] was of the first ones.

If the structure tensor  $F$  is parallel (*i.e.*  $(\nabla_X F)Y = 0$ , where  $\nabla$  is the Riemannian connection), then  $M$  is called K-manifold.

If the structure tensor  $F$  satisfies the condition  $(\nabla_X F)Y = 0$ , for arbitrary vector field  $X$  on  $M$ , then  $M$  is called nearly K-manifold (briefly NK-manifold).

In the present communication we deal with some  $2m$ -dimensional H-structure manifolds. In the second section we shall give some useful preliminaries. In the last section we shall give the main result of the present communication, which are referred in [1].

## II. PRELIMINARIES

Let  $\phi$  be  $(0,2)$ -tensor on a  $2m$ -dimensional H-structure manifold  $M$  such that

$$\phi(X, Y) = g(FX, Y) = -g(X, FY). \quad (2)$$

Using (2) we can prove:

$$\phi(X, Y) + \phi(Y, X) = 0, \quad (3)$$

$$\phi(FX, FY) + a^r \phi(X, Y) = 0, \quad (4)$$

$$(\nabla_X \phi)(Y, Z) + (\nabla_X \phi)(Z, Y) = 0, \quad (5)$$

$$(\nabla_X \phi)(FY, FZ) = a^r (\nabla_X \phi)(Y, Z). \quad (6)$$

Denoting by  $(W, X, Y, Z) = g((\nabla_W F)X, (\nabla_Y F)Z)$ , the properties (3) and (4) give:

$$\begin{aligned} (W, X, Y, Z) &= (Y, Z, W, X), \\ (W, FX, Y, FZ) &= -a^r (W, X, Y, Z), \\ (W, FX, Y, Z) &= -(W, X, Y, FZ), \end{aligned} \quad (7)$$

It is well known that the curvature tensor  $R$  is defined by:

$$R_{XY}Z = \nabla_{[X,Y]}Z - [\nabla_X, \nabla_Y]Z.$$

We denote by

$$R(W, X, Y, Z) = g(R_{WX}Y, Z),$$

for arbitrary vector fields  $W, X, Y$  and  $Z$  on  $M$ .

It is also known that the holomorphic sectional curvature  $H(x)$  is defined by

$$H(x) = R(x, Fx, x, Fx) / g(x, x)g(Fx, Fx),$$

for  $x \in Tp(M), (p \in M)$ .

Let  $\{E_1, \dots, E_m, E_{m+1}, \dots, E_{2m}\}$  be an orthonormal frame field such that:

$$E_{m+i} = \sqrt{-1}E_i / a^{r/2}, (i = 1, \dots, m).$$

We denote by  $k$  and  $k^*$  the Ricci tensor and the Ricci \*tensor on M, respectively. The Ricci \*tensor  $k^*$  is defined by

$$k^*(x, y) = \text{trace of } (z \rightarrow R(Fz, x)Fy),$$

for  $x, y, z \in T_p(M), p \in M$ .

**3. MAIN RESULTS**

In the present section we shall state the main results of the present communication.

**Theorem 1**

Let M be on H-structure manifold of pointwise constant holomorphic sectional curvature c(p). Then

$$\begin{aligned} 4a^r c(p) [ -2\phi(x, y)Fw - \phi(x, w)Fy + \phi(y, w)Fx + a^r g(x, w)y - a^r g(y, w)x ] = \\ = -3a^{2r} R(w, x)y + 3FR(Fw, Fx)Fy + a^r R(Fw, Fx)y - a^r FR(w, x)Fy - \\ a^r R(Fw, x)Fy - 3a^r FR(Fw, x)y + 3a^r R(w, Fx)Fy + a^r FR(w, Fx)y + \\ 3a^r R(w, y)x - 3FR(Fw, Fy)Fx - a^r R(Fw, Fy)x + a^r FR(w, y)Fx + \\ a^r R(Fw, y)Fx + 3a^r FR(Fw, y)x - 3a^r R(w, Fy)Fx - a^r FR(w, Fy)x. \end{aligned}$$

We now state some lemmas.

**Lemma 1**

If M is an H-structure manifold and  $\{E_i\}$  is an orthonormal frame field, for every vector field X we have:

$$\sum_{i=1}^{2m} [R(X, FE_i)]FE_i + a^r R(X, E_i)E_i = 0,$$

$$\sum_{i=1}^{2m} [R(X, E_i)]FE_i + a^r R(X, FE_i)E_i = 0,$$

**Lemma 2**

Let M be a H-structure manifold. Then for arbitrary vector fields X, Y on M we have:

$$k(X, Y) = k(Y, X)$$

$$k^*(FX, FY) = -a^r k^*(Y, X)$$

$$k(FX, Y) = -k^2(FY, X).$$

If  $s$  and  $s^*$  are the scalar and the \*scalar curvatures of M respectively, then we have:

**Proposition 1**

If M be a 2m-dimensional H-structure manifold of pointwise constant holomorphic sectional curvature c(p), then for arbitrary vector fields X, Y on M, we have:

$$\begin{aligned} a^r k(X, Y) &= k(FX, FY) - 3[k^*(X, Y) + k^*(Y, X)] \\ &= 4(m+1)c(p)a^r g(X, Y), \\ a^r s - 3s &= 4m(m+1)a^r c(p). \end{aligned}$$

The results of the theorem 1 and the proposition 1 have been obtained by G.B. Rizza for  $a^{r/2} = -1, ([5])$ .

For every NK-manifold we have:

$$k(X, Y) = (a^r - 3)^{-1} \sum_{im1}^{2m} (X, E_i, Y, E_i),$$

$$k(FX, FY) = -a^r k(X, Y),$$

$$k^*(X, Y) = k^*(Y, X),$$

$$k^*(X, Y) = (a^r - 3)^{-1} a^r k(X, Y).$$

Using the above relations we can obtain the following:

**Theorem 2**

If M is a 2m-dimensional connected NK-manifold of pointwise constant holomorphic sectional curvature, then M is an Einstein manifold.

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