Hsu-Structure Manifold on Affine Connexions

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Abstract— — In this paper we have studied some affine connexions in a Hsu-structure manifold. Certain theorems have also been proved, which are of great geometrical importance.

Index Terms— C^{∞} -manifold, Hsu-structure, Hsu-metric structure, F-structure, π -structure

I. INTRODUCTION

We consider a differentiable manifold V_n of differentiability class C^{∞} and of dimension n. Let there exist in V_n a tensor field F of the type (1, 1), s linearly independent vector fields U_i , i=1,2,...,s and s linearly independent 1-forms

 u^{i} such that for any arbitrary vector field X, we have

$$X = a^r X + c u^i(X) U_i, \qquad (1.1)$$

$$\overline{U}_i = p_i^j U_j \tag{1.2}$$

Where

 $F(X) \stackrel{def}{=} \overline{X}$ and a^r , *c* are constants Then the structure $\{F, u^i, U_i, p_i^j; i, j=1, 2, \dots, s\}$ will be known as Hsu-structure and V_n will be known as Hsu-structure manifold of order s where s < n.

Definition: A structure on an n-dimensional manifold M of class C^{∞} given by a non-null tensor field F satisfying $F^2 = a^r I$

is called
$$\pi$$
 - structure or Hsu-structure, where a is a non zero complex constant and I denotes the unit tensor field. Then M is called π - structure manifold or Hsu-structure manifold[8].

Agreement 1.1

All the equations which follow hold for arbitrary vector fields X, Y, Z etc.

Now replacing
$$X$$
 by X in (1.1), we get

$$\overline{\overline{X}} = a^r \,\overline{X} + c \, u^i \left(\overline{X}\right) U_i \tag{1.3}$$

Operating F in (1.1), we get

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$$\overline{\overline{X}} = a^r \overline{X} + c u^i(X) \overline{U_i}$$
Using (1.2) in above, we get
$$\overline{\overline{\overline{X}}} = a^r \overline{X} + c u^i(X) p_i^j U_j \qquad (1.4)$$

From (1.3) and (1.4), we have

$$u^{i}(\overline{X}) = u^{j}(X) p_{j}^{i}$$
(1.5)

Further, operating F in (1.2) and using (1.1 and (1.2), we get ⁽²⁾ $p_i^j = a^r \, \delta_i^j + c u^j \, (U_i)$ (1.6)

Where

$${}^{(r)}p_{j}^{i} = {}^{(r-1)}p_{k}^{i}p_{j}^{k}$$

On Hsu structure manifold V_n , let us introduce a metric tensor g such that F defined by $F(X, Y) \stackrel{def}{=} g(\overline{X}, Y)$ is skew-symmetric, then V_n is called Hsu metric structure manifold.

We have on a Hsu metric structure manifold

$$g(X, Y) + g(X, Y) = 0.$$

Replacing Y by \overline{Y} in above equation and using (1.1), we obtain

 $g(\overline{X}, \overline{Y}) + a^r g(X, Y) + c u^i(X) u^i(Y) = 0$ (1.7) Where

$$u^{i}(X) = g(U_{i}, X)$$
(1.8)

Then V_n satisfying (1.7), (1.8) is called Hsu metric structure manifold[5].

Agreement 1.2: The Hsu metric structure manifold will always be denoted by V_n .

Definitons: [1][4]

Almost tangent metric manifold: A differentiable manifold M_n on which there exists a tensor field F of the type (1, 1)

such that

$$F^2 = 0$$
 (1.9)

is called an almost tangent manifold and $\{F\}$ is called an almost tangent structure on M_n .

On almost tangent manifold, let us introduce a metric g such 'F defined by $F(X, Y) \stackrel{def}{=} g(\overline{X}, Y)$

is alternating. Then M_n is called an almost tangent metric manifold and structure $\{F, g\}$ is called an almost tangent metric structure.

Almost Hermite Manifold: A differentiable manifold

 M_n on which there exists a tensor field F of the type (1, 1) such that

$$F^2 = -I_n \tag{1.10}$$

is called an almost complex manifold and $\{F\}$ is called an almost complex structure.

An almost complex manifold endowed with an almost complex structure and a metric g such that

$$g(X,Y) = g(X,Y) \tag{1.11}$$

is called an almost Hermite manifold and structure

 $\{F, g\}$ is called an almost Hermite structure.

Metric π -structure manifold:

A differentiable manifold M_n on which there exists a tensor field F of the type (1, 1) such that

$$F^2 = -\lambda^r I_n \tag{1.12}$$

where λ is a non zero complex constant. Then $\{F\}$ is called a

 π – structure or Hsu structure and M_n is called

 π – structure manifold or Hsu structure manifold.

On almost tangent manifold, let us introduce a metric g such that F is defined by

 $F(X, Y) \stackrel{def}{=} g(\overline{X}, Y)$ is alternating.

Then $\{F, g\}$ is called metric π – structure or H-structure

and M_n is called metric π – structure manifold or

H-structure manifold[7][3].

F-structure Manifold: Let M_n be an n dimensional

differentiable manifold of class C^{∞} and let there be a tensor field of type (1, 1) and rank $r(1 \le r \le n)$ everywhere such that

$$F^{3} + F = 0 \tag{1.13}$$

Then $\{F\}$ is called an F-structure and M_n is called F-structure manifold[9].

Almost Grayan manifold: If on an differentiable manifold M_n (n = 2m+1) of differentiability class C^{r+1} , there exist a tensor field F of type (1, 1), a 1-form u and a vector field U, satisfying

$$F^2 = -I_n + u \otimes U \tag{1.14}$$

and

 $\overline{U} = 0 \tag{1.15}$

Then M_n is called an almost contact manifold and the structure $\{F, U, u\}$ is said to give an almost contact

structure to
$$M$$

On an almost contact manifold, let us introduce a metric g such that F defined by

 $F(X, Y) \stackrel{def}{=} g(\overline{X}, Y)$ is skew symmetric. Then M_n is called an almost Grayan manifold and the structure

 $\{F, g, U, u\}$ is called an almost Grayan structure[10]. In this manifold it can be easily calculated

$$g(\overline{X},\overline{Y}) = g(X,Y) - u(X)u(Y) = 0$$
(1.16)

Torsion tensor: A vector valued, skew-symmetric, bilinear function S defined by

$$S(X, Y) = D_X Y - D_Y X - [X, Y]$$
 (1.17)

is called torsion tensor of a connexion D in a C^{∞} manifold V_n .

For the symmetric or torsion free connexion D, the torsion tensor vanishes.

Curvature tensor: The tensor K of the type (1, 3) defined by def

$$K(X, Y, Z) = D_X D_Y Z - D_Y D_X Z - D_{[X,Y]} Z$$
(1.18)

is called the curvature tensor of the connexion D. *Remark 1.1*

It may be noted that V_n gives an almost tangent metric manifold, an almost Hermite manifold, metric π -structure manifold, F-structure manifold, an almost Grayan manifold and $\{F, g, u^1, u^2, U_1, U_2\}$ structure manifold according as $(a^r = 0, c = 0); (a^r = -1, c = 0);$ $(a^r = \lambda^r, c = 0); (a^r = -1, p_i^j = 0);$ $(a^r = -1, c = 1, i, j = 1, p_1^1 = 0)$ and $(a^r = -1, c = 1, p_i^j + p_j^i = 0; i, j = 1, 2)$ respectively.

Affine Connexion D: Let us consider in V_n an affine

connection D satisfying[2][6]

$$(D_X F)Y = 0$$
 (2.1)a

and we call it as F-connexion.

(2.1)a is equivalent to

$$D_X \,\overline{Y} = D_X Y \tag{2.1}b$$

Replacing Y by \overline{Y} and using (1.1), (2.1)a in above, we get

$$c[u^{i}(Y)D_{X}U_{i} + (D_{X}u^{i})(Y)U_{i}] = 0$$
 (2.1)c

Theorem 2.1

 $\ln V_n$, we have

$$cu^{i}(Y)u^{j}(D_{X}U_{i}) = -(a^{r}\delta_{i}^{j} - {}^{(2)}p_{i}^{j})(D_{X}u^{i})(Y) \quad (2.2)$$

$$cu^{j}(D_{X}U_{i})U_{i} = -(a^{r}\delta_{i}^{j} - {}^{(2)}p_{i}^{j})(D_{X}U_{i}) \quad (2.2)$$

$$cu^{\prime}(D_{X}U_{i})U_{j} = -(a^{\prime}\delta_{i}^{\prime} - {}^{(2)}p_{i}^{\prime})(D_{X}U_{j})$$
(2.3)
Proof

Operating u^{j} in (2.1)c and using (1.6), we get (2.2).

Putting U_i for Y in (2.1)c and using (1.6), we obtain (2.3).

Theorem 2.2

 $\ln V_n$, we have

$$S(\overline{X},\overline{Y}) + a^{r}S(X,Y) + cu^{i}(S(X,Y))U_{i} - S(\overline{X},Y) - S(X,\overline{Y})$$

$$= -\left[\overline{X}, \overline{Y}\right] - a^{r} \left[X, Y\right] - c u^{i} \left(\left[X, Y\right]\right) U_{i} + \overline{\left[\overline{X}, Y\right]} + \overline{\left[\overline{X}, \overline{Y}\right]} (2.5)$$
Proof

From (2.1)b, we get

$$D_{\overline{X}}\overline{Y} = \overline{D_{\overline{X}}Y}, D_{\overline{Y}}\overline{X} = \overline{D_{\overline{Y}}X}, \overline{D_{X}}\overline{\overline{Y}} = \overline{D_{X}Y}, \overline{D_{Y}}\overline{\overline{X}} = \overline{\overline{D_{Y}}X}$$
(2.6)
Now in view of (1.1), we get

$$S(\overline{X},\overline{Y}) + a^{r}S(X,Y) + cu^{i}(S(X,Y))U_{i} - \overline{S(\overline{X},Y)} - \overline{S(X,\overline{Y})}$$
$$= S(\overline{X},\overline{Y}) + \overline{S(\overline{X},Y)} - \overline{S(\overline{X},Y)} - \overline{S(\overline{X},\overline{Y})} - \overline{S(X,\overline{Y})}$$

Using (1.17) and (2.6) in right hand side of above, we get (2.5). Now, we consider in V_n a scalar valued bilinear function μ , vector valued linear function ν and a 1-form σ given by,

$$\mu(X,Y) \stackrel{\text{def}}{=} (D_Y u^i)(\overline{X}) - (D_X u^i)(\overline{Y}) + (D_{\overline{Y}} u^i)(X) - (D_{\overline{X}} u^i)(Y)$$
(2.7)

$$v(X) = (D_{U_i} F)(X) - (D_X F)(U_i) - D_{\overline{X}} U_i$$
(2.8)

and

$$\sigma(X) \stackrel{def}{=} (D_X u^j) (U_i) - (D_{U_i} u^j) (X)$$

$$i, j = 1, 2, \dots, s.$$
(2.9)

Theorem 2.3

 $\ln V_n$, we have

$$(a^{r} \delta_{i}^{j} - {}^{(2)} p_{i}^{j}) \mu(X, Y) = c[u^{i}(X)u^{j}(D_{\overline{Y}}U_{i}) - u^{i}(Y)u^{j}(D_{\overline{X}}U_{i}) - u^{i}(\overline{X})(D_{Y}u^{j})U_{i} + u^{i}(\overline{Y})(D_{X}u^{j})U_{i}]$$
(2.10)a
$$(a^{r} \delta_{i}^{j} - {}^{(2)}p_{i}^{j})\mu(X, Y) = -c[u^{i}(X)u^{j}(v(Y)) - u^{i}(Y)u^{j}(v(X)) + u^{i}(\overline{X})(D_{Y}u^{j})U_{i} - u^{i}(\overline{Y})(D_{X}u^{j})U_{i}]$$
(2.10)b

and

$$(a^{r} \delta_{i}^{j} - {}^{(2)} p_{i}^{j}) \mu(X, Y) = -c[u^{i}(X) \{ \sigma(\overline{X}) + (D_{U_{i}} u^{j})(\overline{X}) \}$$
$$-u^{i}(Y) \{ \sigma(\overline{Y}) + (D_{U_{i}} u^{j})(\overline{Y}) \} - u^{i}(\overline{X})(D_{Y} u^{j})U_{i}$$
$$+u^{i}(\overline{Y})(D_{X} u^{j})U_{i}]$$
(2.10)c

Proof

Replacing Y by \overline{Y} in (2.2), we get $cu^{i}(\overline{Y})u^{j}(D_{x}U_{i}) = -(a^{r}\delta_{i}^{j}-{}^{(2)}p_{i}^{j})(D_{x}u^{i})(\overline{Y})$ (2.11)

Replacing X by \overline{X} in (2.2), we get $cu^{i}(Y)u^{j}(D_{\overline{X}}U_{i}) = -(a^{r}\delta_{i}^{j} - {}^{(2)}p_{i}^{j})(D_{\overline{X}}u^{i})(Y)$ (2.12) Further by using (2.11), (2.12) in (2.7), we get (2.10)a. Using (2.1)a in (2.8), we get (2.13) $v(X) = -(D_{\overline{x}}U_i)$

Using (2.13) in (2.10)a, we get (2.10)b. Replacing X by \overline{X} in (2.9), we get

$$-u^{j}(D_{\overline{X}}U_{i}) = \sigma(\overline{X}) + (D_{U_{i}}u^{j})(\overline{X})$$

$$(2.14)$$
Using (2.14) in (2.10), we get (2.10).

Using (2.14) in (2.10)a, we get (2.10)c.

In V_n , we have

$$K(X,Y,\overline{Z}) = a^{r}K(X,Y,Z) + cu^{i}(K(X,Y,Z))U_{i} \quad (2.16)a$$

$$p_{i}^{j}u^{i}(K(X,Y,\overline{Z})) = a^{r}u^{j}(K(X,Y,Z))$$

$$+ ({}^{(2)}p_{i}^{j} - a^{r}\delta_{i}^{j})u^{i}(K(X,Y,Z)) \quad (2.16)b$$

and

$$a^{r} \left[K(\overline{X}, \overline{Y}, Z) + K(\overline{Y}, \overline{Z}, X) + K(\overline{Z}, \overline{X}, Y) \right] = -c[u^{i}(Z)K(\overline{X}, \overline{Y}, U_{i}) + u^{i}(X)K(\overline{Y}, \overline{Z}, U_{i}) + u^{i}(Y)K(\overline{Z}, \overline{X}, U_{i})]$$
(2.16)c

Proof

Replacing Z by \overline{Z} in (1.18) and using (2.1)b, we get $K(X,Y,\overline{Z}) = \overline{K(X,Y,Z)}$ (2.17)

Operating F in (2.17) and using (1.1), we obtain (2.16)a.

Operating u^{j} on both sides of (2.16)a and using (1.5) and (1.6), we get (2.16)b. Bianchi's first identity of symmetric connexion D is given by

$$K(X,Y,Z) + K(Y,Z,X) + K(Z,X,Y) = 0$$
 (2.18)
Operating F in (2.18), we get

$$\overline{K(X,Y,Z)} + \overline{K(Y,Z,X)} + \overline{K(Z,X,Y)} = 0$$
(2.19)
Using (2.17) in (2.19), we get

$$K(X,Y,\bar{Z}) + K(Y,Z,\bar{X}) + K(Z,X,\bar{Y}) = 0$$
 (2.20)

Replacing X by \overline{X} , Y by \overline{Y} and Z by \overline{Z} in (2.20) and using (1.1), we get (2.16)c.

Affine connexion \tilde{D} : Let us consider in V_n an affine

connexion
$$D$$
 satisfying
 $u^{i}(Y)(\widetilde{D}_{X}U_{i}) + cu^{j}(\widetilde{D}_{X}u^{i})(Y)U_{i} = 0$ (3.1)

Theorem 3.1 In V_{n} , we have

$$u^{i}(Y) \Big[a^{r} (\tilde{D}_{X} U_{i}) + c u^{j} (\tilde{D}_{X} U_{i}) U_{j} \Big] \\ + (\tilde{D}_{X} u^{i}) (Y) p_{i}^{j} p_{j}^{k} U_{k} = 0$$
(3.2)a

$${}^{(2)}p_{i}^{j} - a^{r}\delta_{i}^{j})div U_{j} = cu^{j}(\widetilde{D}_{U_{j}}U_{i})$$
 (3.2)b

Where

$$div X \stackrel{def}{=} (C_1^1 \nabla X) \tag{3.3}$$

 $(\nabla X)Y \stackrel{def}{=} (\tilde{D}_Y X)$ (3.4)Proof

Operating F^2 in (3.1) and using (1.1) and (1.2), we get (3.2)a. Now contracting (3.1) with respect to X and using (3.3) and (3.4), we get

$$u^{i}(Y)div U_{i} + (\tilde{D}_{U_{i}}u^{i})(Y) = 0$$
(3.5)

Replacing i by j, then Y by U_i in (3.3) and using (1.6), we get (3.2)b.

Theorem 3.2

In
$$V_n$$
, we have
 $cu^i(Y)u^j(\widetilde{D}_XU_i) + {}^{(2)}p^j_i - a^r\delta^j_i)(\widetilde{D}_Xu^i)(Y) = 0$ (3.6)a
 ${}^{(2)}p^j_i - a^r\delta^j_i)(\widetilde{D}_Xu^i)(Y)u^j(\widetilde{D}_ZU_i) =$
 $cu^i(Y)u^j(\widetilde{D}_ZU_j)(\widetilde{D}_Xu^j)(U_j)$ (3.6)b

Proof

By operating u^{\prime} on (3.1) and using (1.6), we obtain (3.6)a. Multiplying (3.2)a with $u^{j}(\tilde{D}_{Z}U_{j})$, we get (3.6)b.

Affine connexion D

Let us consider in V_n an affine connexion D satisfying

$$u^{i}(Y)(D_{X}U_{i}) + (D_{X}u^{i})(Y)U_{i} = 0$$
 (4.1)a

and

$$(D_X F)(Y) + (D_Y F)(X) = 0$$
(4.1)b
way he noted that all the results of the section above hold

It may be noted that all the results of the section above hold

for D. In addition we have the following results:

Theorem 4.1

In V_n , we have

$$\overline{D_{X}^{\circ} \overline{Y}} + \overline{D_{Y}^{\circ} \overline{X}} - a^{r} (D_{X}^{\circ} Y + D_{Y}^{\circ} X) = c \left[u^{i} (D_{X}^{\circ} Y) + u^{i} (D_{Y}^{\circ} X) \right] U_{i} \qquad (4.2)s$$

$$\overset{\circ}{D_{\overline{Y}}} \overline{X} - a^r (\overset{\circ}{D_Y} X) = \overset{\circ}{D_{\overline{Y}}} X - \overset{\circ}{D_Y} \overline{X} + cu^i (\overset{\circ}{D_Y} X) U_i$$
(4.2)b

and

$$\overset{\circ}{D_{\overline{Y}}} \overline{X} + a^{r} (\overset{\circ}{D_{Y}} \overline{X} - \overset{\circ}{D_{Y}} X - \overset{\circ}{D_{\overline{Y}}} X) = c \left[\left\{ u^{i} (\overset{\circ}{D_{\overline{Y}}} X) - u^{i} (\overset{\circ}{D_{Y}} \overline{X}) \right\} U_{i} + u^{i} (\overset{\circ}{D_{Y}} X) \overline{U_{i}} \right] (4.2)c$$
Proof

Proof

The equation (4.1)b is equivalent to

$$D_X \overline{Y} + D_Y \overline{X} = D_X Y - D_Y X$$
(4.3)
Promoting *D* in (4.2) and using (1.1), we get (4.2) a Paralaging

Operating F in (4.3) and using (1.1), we get (4.2)a. Replacing Y by \overline{Y} in (4.3) and using (1.1), (4.3), we get (4.2)b. Further, Operating F in (4.2)b and using (1.1), we get (4.2)c.

Affine connexion D

Let us consider in V_n an affine connexion D satisfying

$$u^{i}(Y)(D_{X}^{*}U_{i}) + (D_{X}^{*}u^{i})(Y)U_{i} = 0$$
 (5.1)a

and

$$(D_X^* F)(Y) + (D_{\overline{X}}^* F)(\overline{Y}) = 0$$
 (5.1)b

It may be noted that all the results of the section three hold for

D. In addition we have the following results:

Theorem 5.1

 $\ln V_n$, we have

$$\frac{D_{X}^{*}Y + D_{\overline{X}}^{*}\overline{Y} - D_{X}^{*}\overline{Y} = a^{r}(D_{\overline{X}}^{*}Y) + cu^{i}(D_{\overline{X}}^{*}Y)U_{i} (5.2)a}{D_{U_{j}}^{*}\overline{Y} + (D_{U_{j}}^{*}F)\overline{Y} = a^{r}(D_{U_{j}}^{*}Y) + cu^{i}(D_{U_{j}}^{*}Y)U_{i} (5.2)b}$$
Proof

(5.1)b is equivalent to

$$D_{X}^{*}Y + D_{\overline{X}}^{*}\overline{Y} = D_{X}^{*}\overline{Y} + D_{\overline{X}}^{*}\overline{\overline{Y}}$$
(5.3)

Using (1.1) in (5.3), we get (5.2)a. Replacing X by U_i in (5.3), we get

$$(D_{U_i}^*\overline{Y} + \overline{D_{U_i}^*Y}) + p_i^j \left[D_{U_j}^*a^rY + cu^i(Y)U_i \right] = p_i^j (\overline{D_{U_j}}\overline{Y})$$
(5.4)

Replacing X by U_i in (5.2)b, we get

$$(D_{U_{i}}^{*}\overline{Y} - D_{U_{i}}^{*}Y) = -p_{i}^{j}(D_{U_{i}}^{*}F)\overline{Y}$$
(5.5)
From (5.4) and (5.5), we get
$$-p_{i}^{j}(D_{U_{i}}^{*}F)\overline{Y} + p_{i}^{j}\left[D_{U_{j}}^{*}a^{r}Y + cu^{i}(Y)U_{i}\right] = p_{i}^{j}(\overline{D_{U_{j}}^{*}\overline{Y}})$$

(5.6)

Using (5.1)a in (5.6), we get (5.1)b.

Theorem 5.2

 $\ln V_n$, we have

$$\sum_{\overline{X}}^{*} \overline{Y} - a^{r} (D_{X}^{*} \overline{Y} + a^{r} (D_{X}^{*} Y) = D_{\overline{X}}^{*} \overline{Y} - ca^{r} u^{i} (D_{X}^{*} Y) U_{i}$$

$$+ cu^{i} (X) \left[a^{r} \left\{ (D_{U_{i}}^{*} Y) + u^{j} (D_{U_{i}}^{*} Y) U_{j} \right\} + (D_{U_{i}}^{*} \overline{Y}) \right]$$
(5.7)

Proof

Replacing X by \overline{X} in (5.3) and using (1.1), (5.1), we get (5.7).

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